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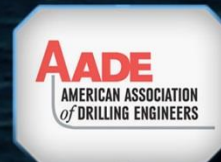


Localization of bubble sources in a water tank for oil spill detection

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Outline



- Introduction
- Experimental setup
- Bubble sounds
- Localization
- Characterization
- Conclusions
- Future works



Introduction

- Detection, localization, and characterization of oil leakages
- Oil leakages create underwater sounds through bubble oscillations
- Active sonar vs passive sonar
- Passive real-time monitoring system

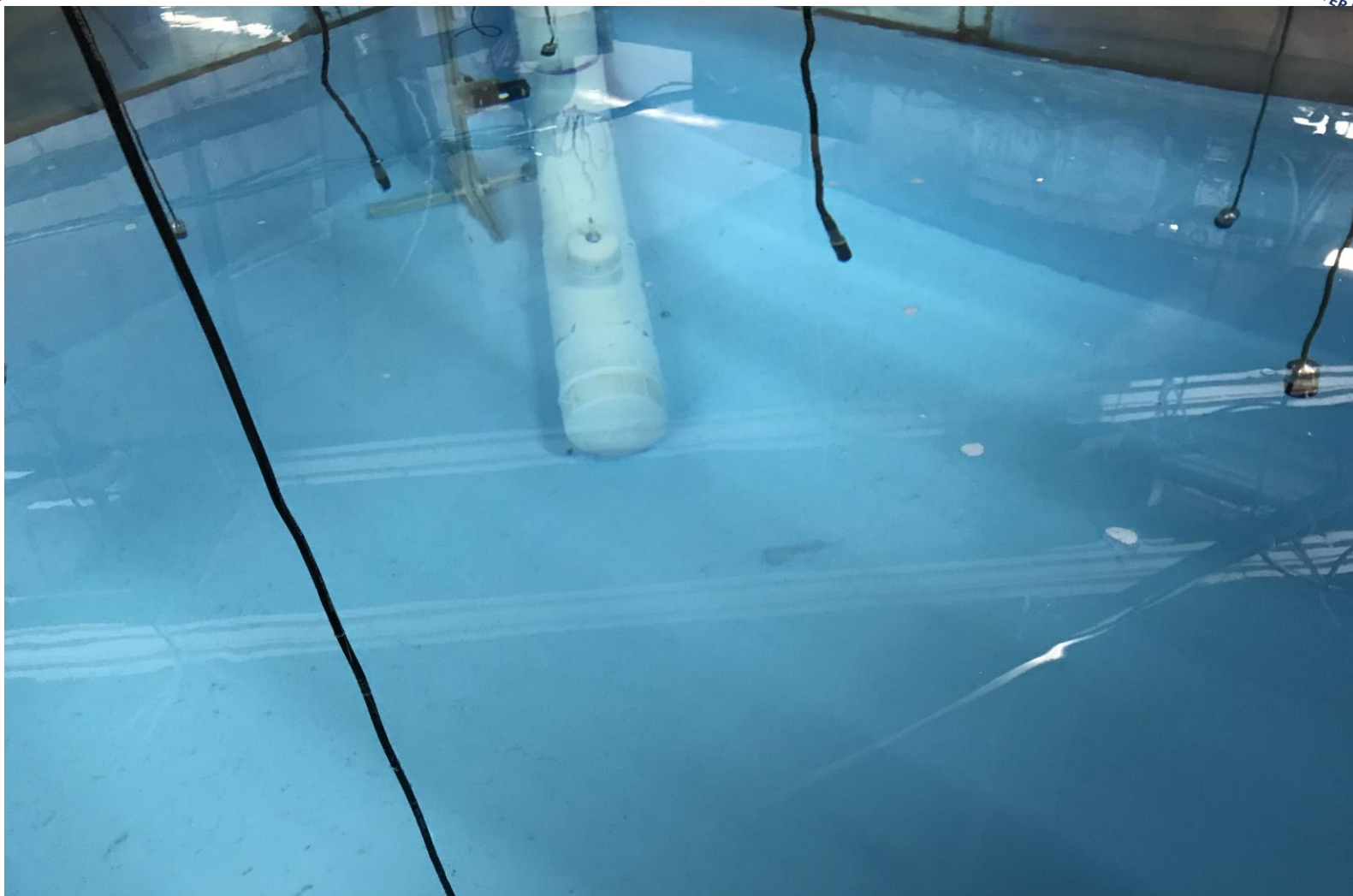


Tasks in this water tank study

- Study oil leakages under controlled conditions
- Develop and test localization algorithms
- Study bubble dynamics and its acoustic characteristics
- Conduct two types of oil leakage studies (a constant flow and a few bubbles)



Experimental setup



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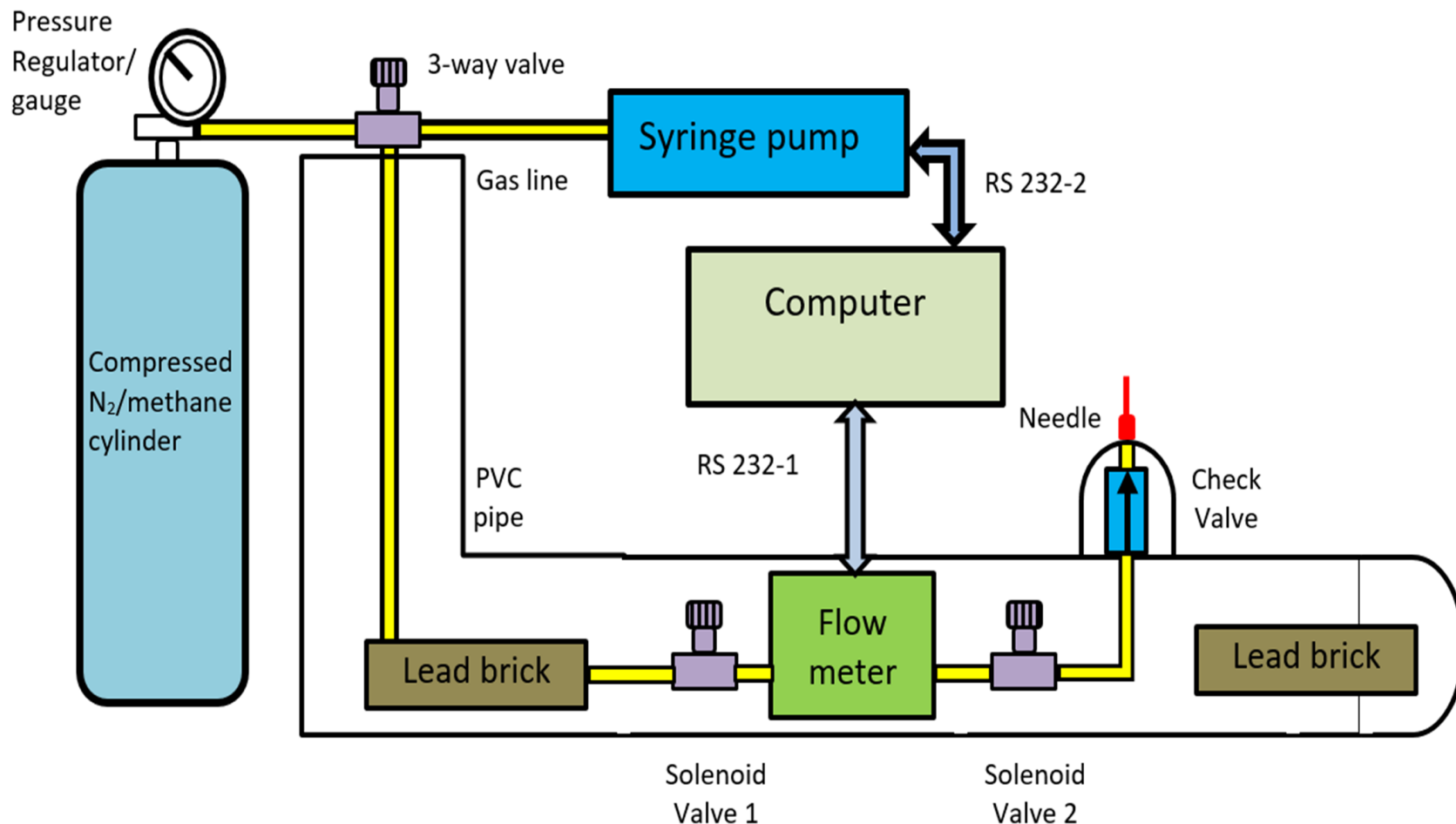
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8'

8'



Bubble generation



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Movie of constant flow

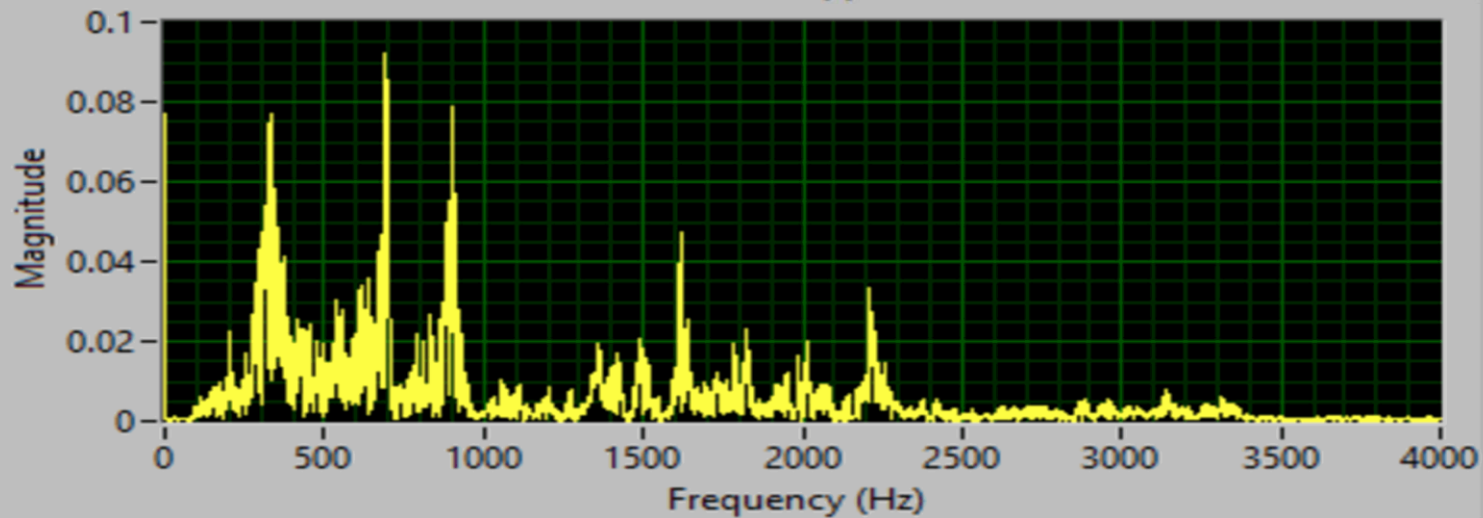
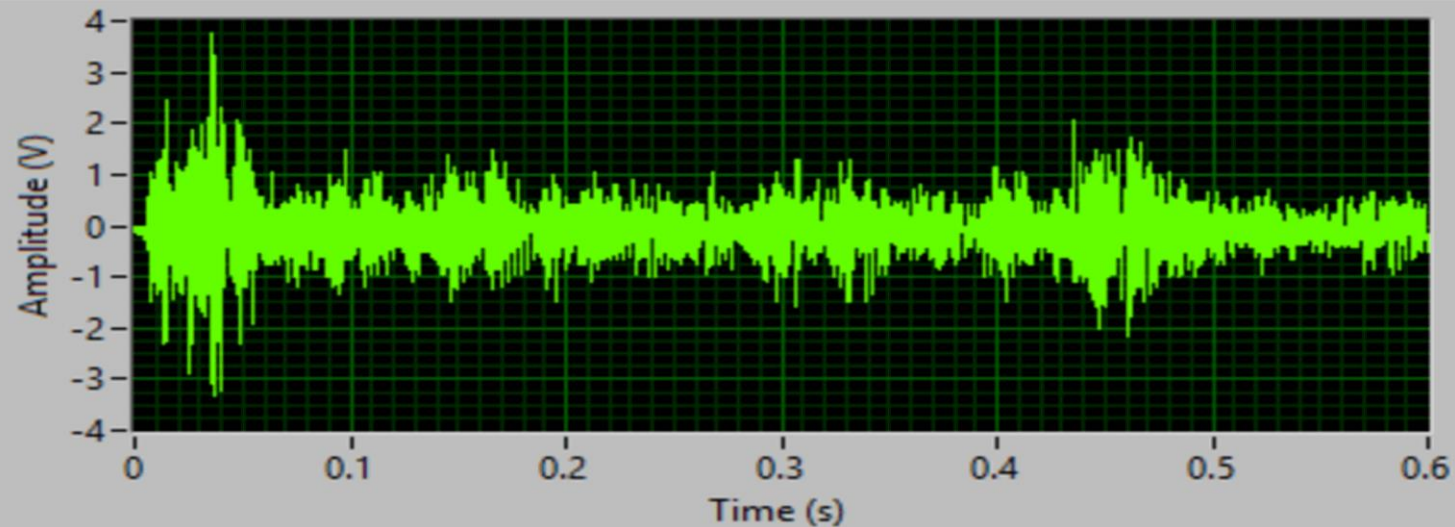


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Sound of constant flow



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Movie of a few bubbles

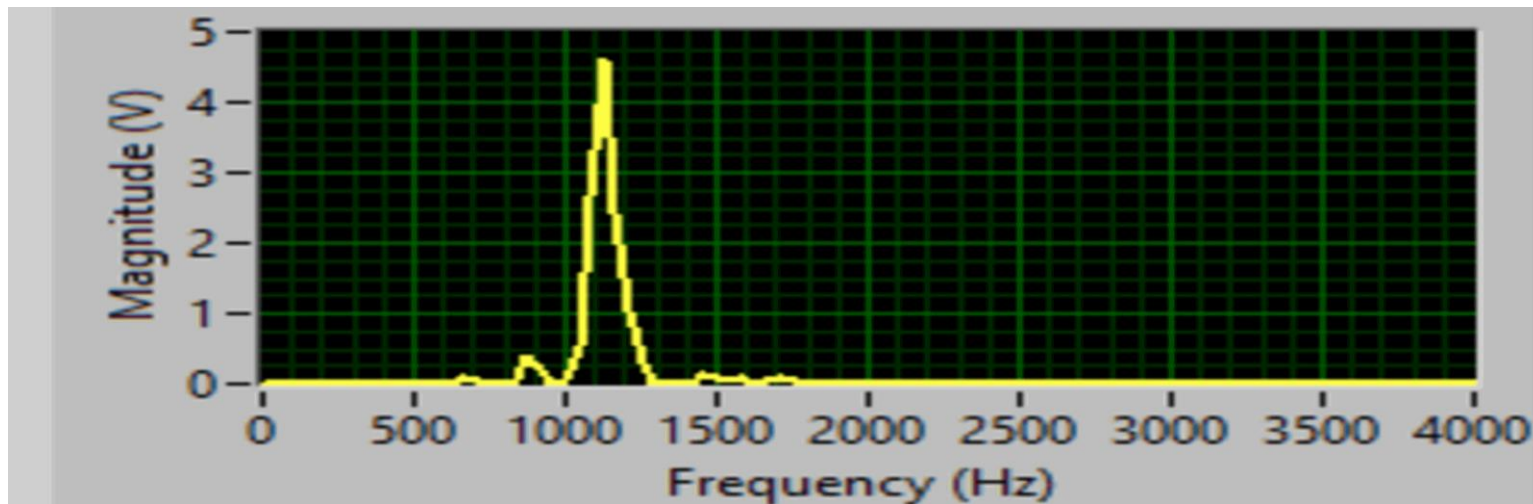
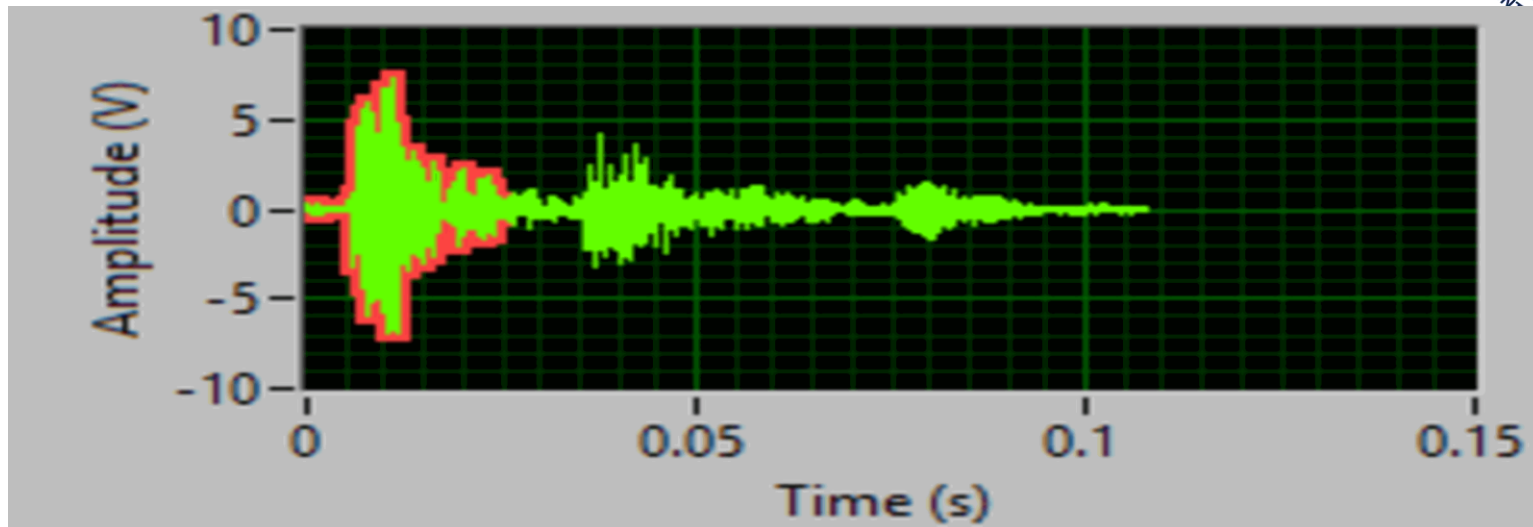


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Sound of a few bubbles

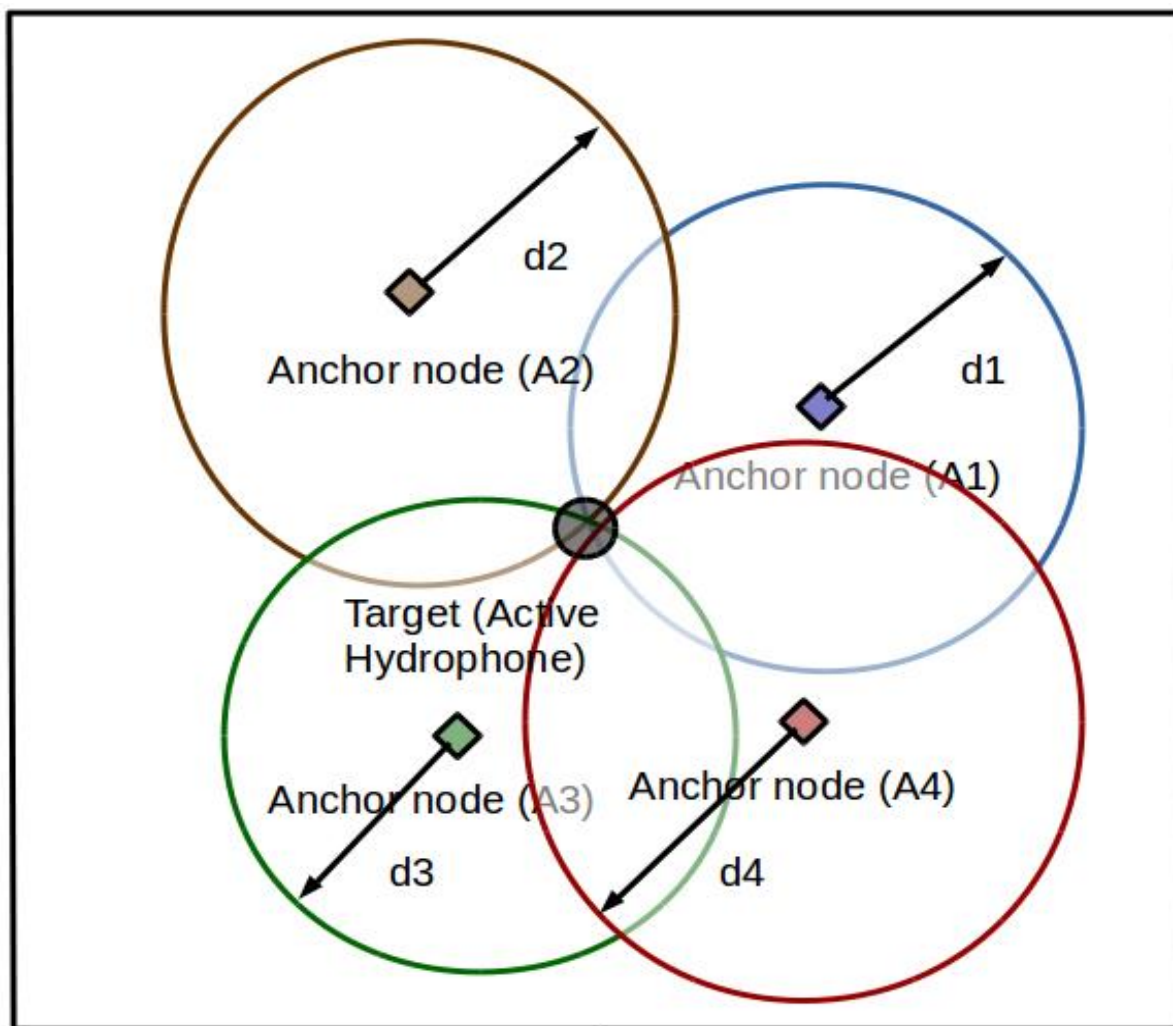


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Localization concept



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Distance equations

$$\left[(x_s - x_1)^2 + (y_s - y_1)^2 + (z_s - z_1)^2 \right]^{1/2} = c \cdot \Delta t_1$$

$$\left[(x_s - x_2)^2 + (y_s - y_2)^2 + (z_s - z_2)^2 \right]^{1/2} = c \cdot \Delta t_2$$

•
•
•

$$\left[(x_s - x_N)^2 + (y_s - y_N)^2 + (z_s - z_N)^2 \right]^{1/2} = c \cdot \Delta t_N$$



LSE and TSE algorithms



arrange 3-dimensional co-ordinates of anchor nodes in ascending order of distance from source node

updated anchor node locations = initial anchor node locations - anchor node location closest to the source

Update anchor node location closest to the source to 0

initialize the velocity of the sound

solve the distance equations to get the source node location

arrange 3-dimensional co-ordinates of anchor nodes in ascending order of distance from source node

updated anchor node locations = initial anchor node locations - anchor node location closest to the source

Update anchor node location closest to the source to 0

Initial guess of the source node

initialize the velocity of the sound

initialize delta (error vector)

approximate the distance equations using Taylor series

solve the Taylor series approximated equations for updated error vector (includes TDOA measurements) to get updated error vector

new source location = updated error vector + initial guess of source node

delta = updated error vector

if
error > threshold
then

NO

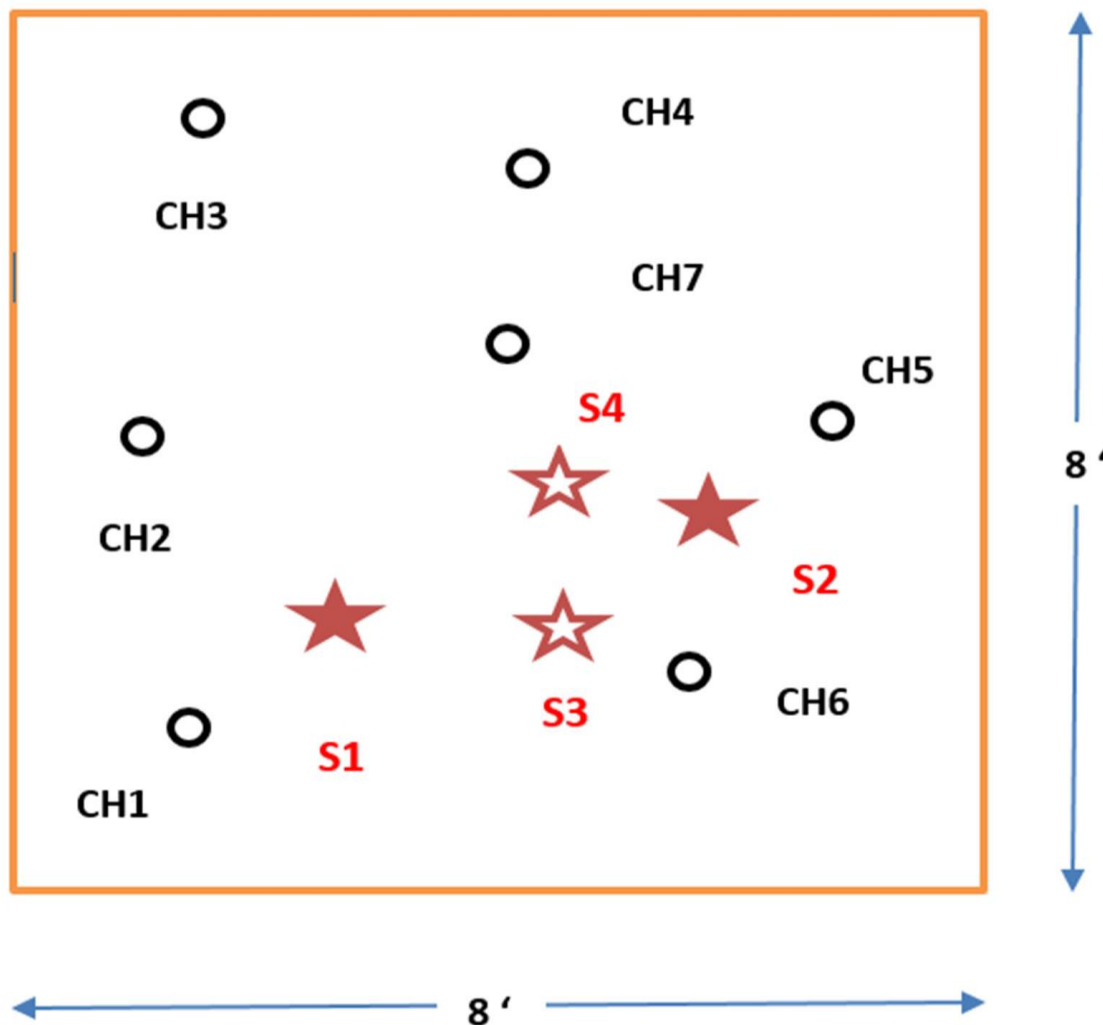
final source location =
new source location

YES

initial guess of the source node = new source location

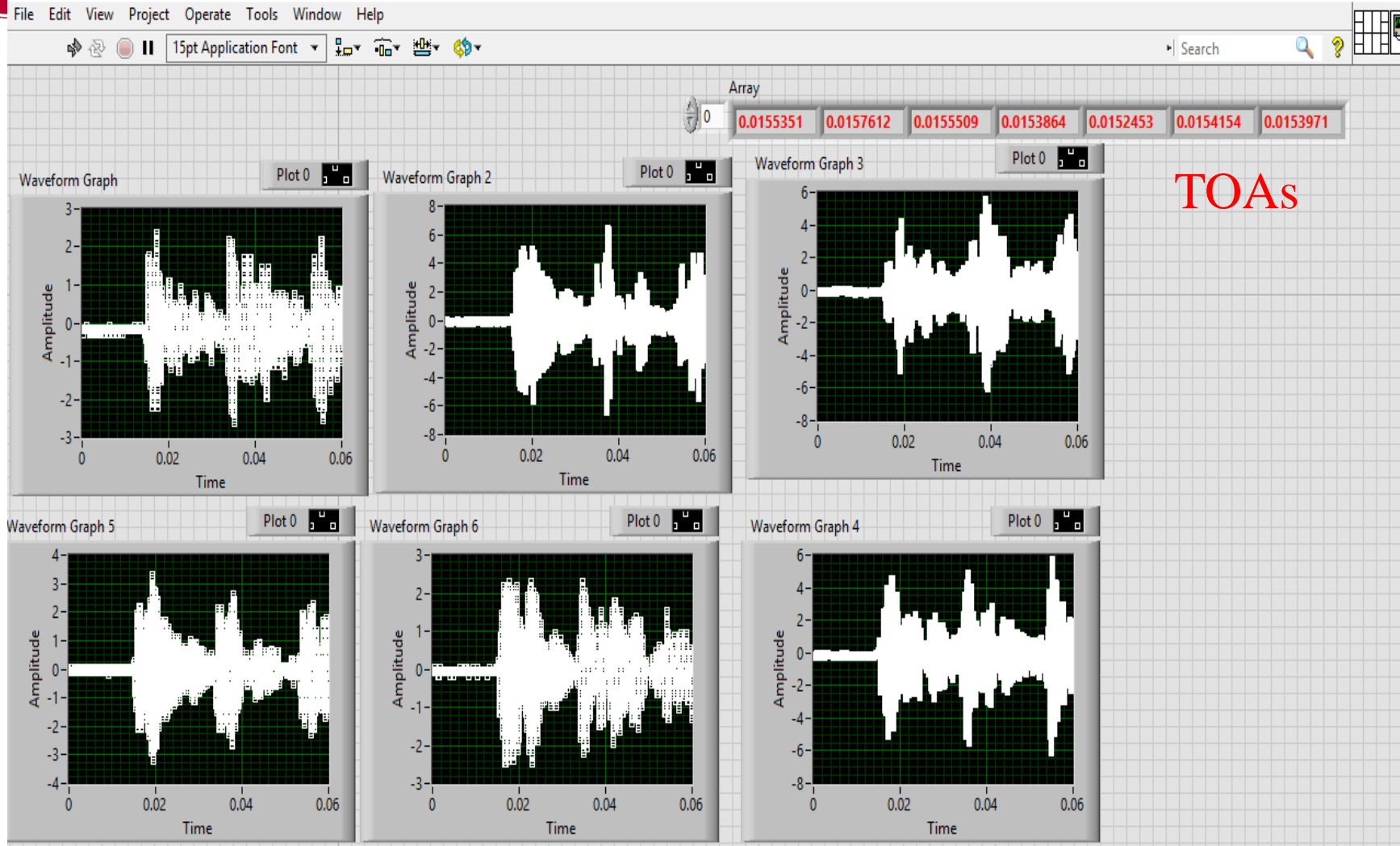


Top view of the setup





6 signals from passive hydrophones



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Results of four sources

Sources	True Location (cm)	Estimated Location (cm)		MSE) (cm)	
		LSE	TSE	LSE	TSE
S1	(174.0, 73.0, 136.0)	(180.6, 75.8, 134.8)	(179.6, 76.7, 135.6)	4.2	3.9
S2	(90.0, 64.0, 115.0)	(90.6, 65.1, 105.5)	(90.3, 65.3, 107.0)	5.5	4.7
S3	(139.5, 52.5, 145.0)	(138.4, 52.4, 151.1)	(136.9, 53.1, 144.0)	3.6	1.7
S4	(136.0, 112.5, 140.0)	(133.4, 115.5, 146.2)	(136.3, 115.6, 145.6)	4.3	3.7

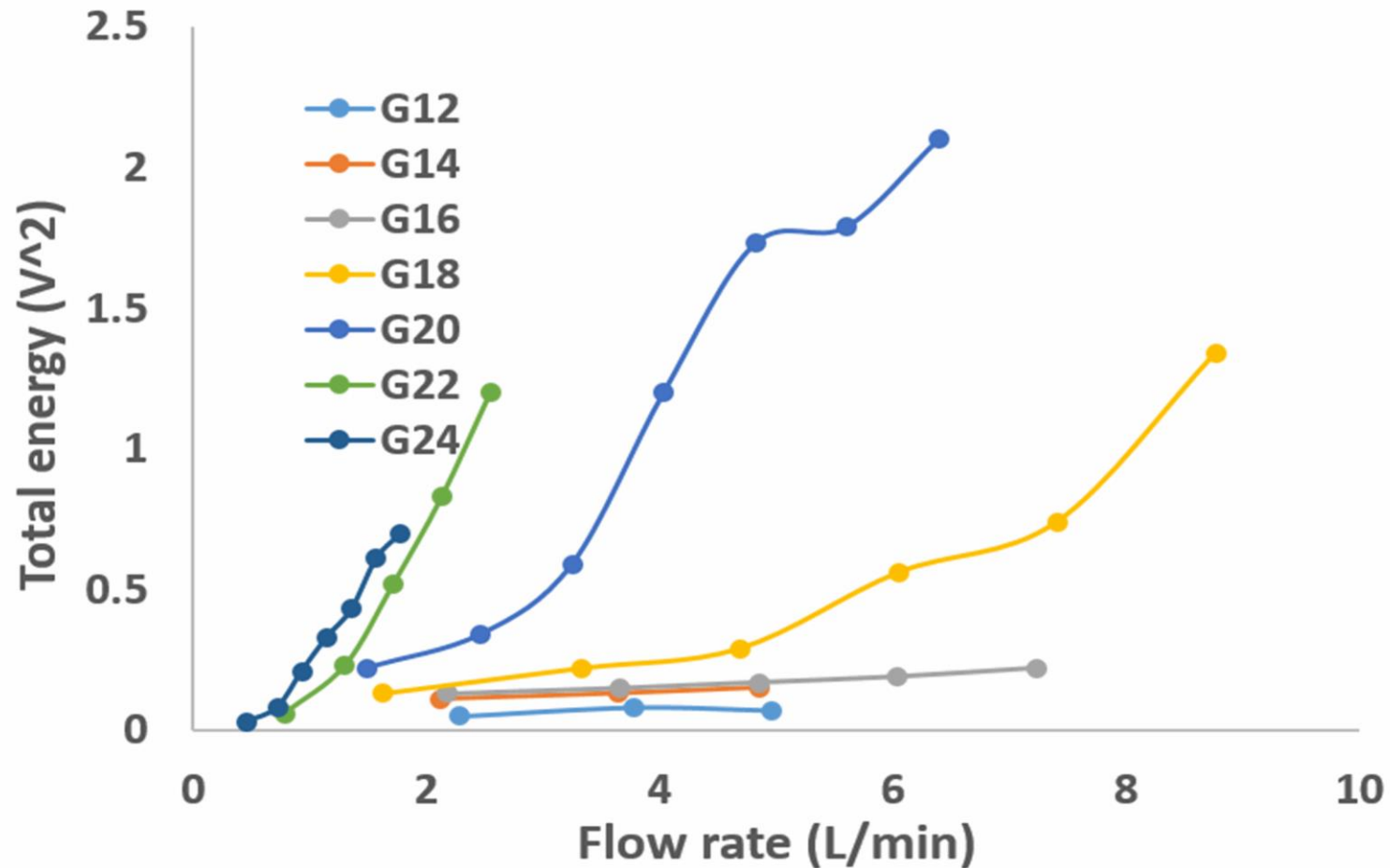


Bubble sound characterization

- Needle diameter
- Flow rate
- Jet velocity
- Total energy
- Resonant frequency

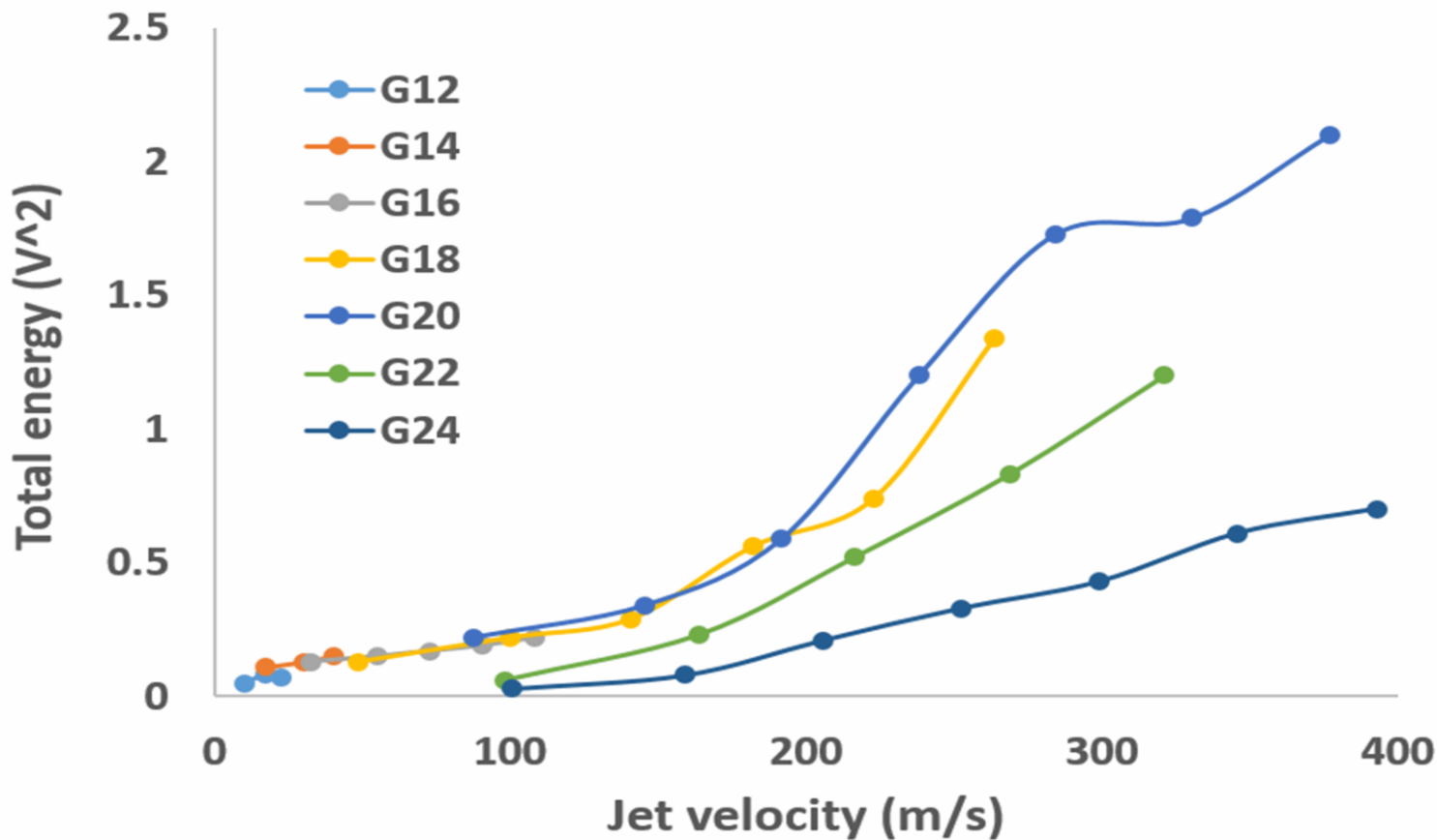


Total energy vs flow rate (for constant flow)



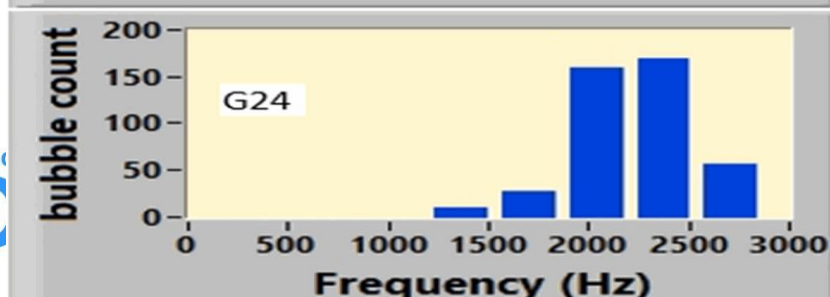
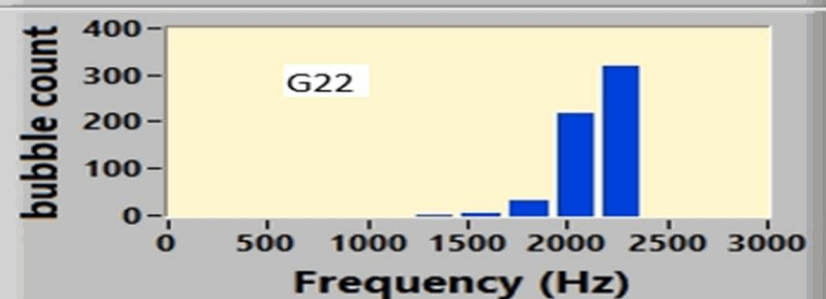
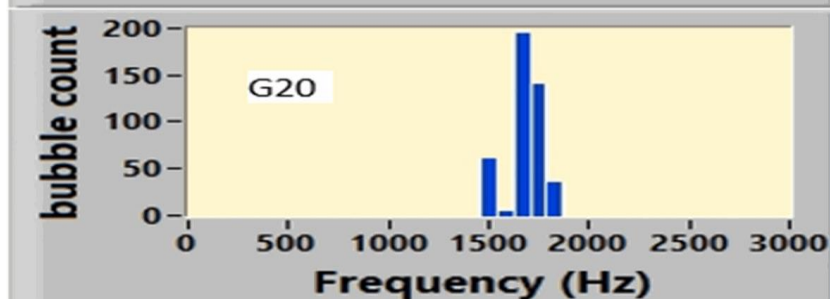
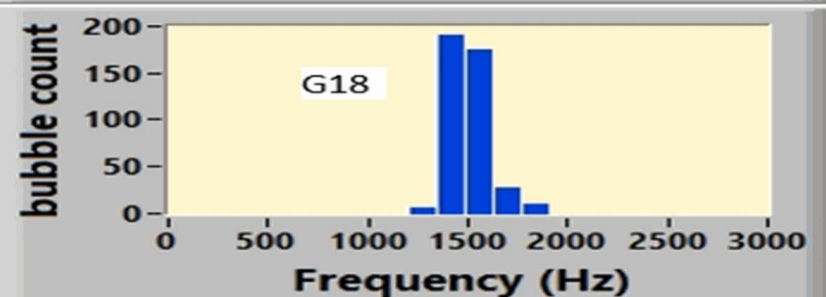
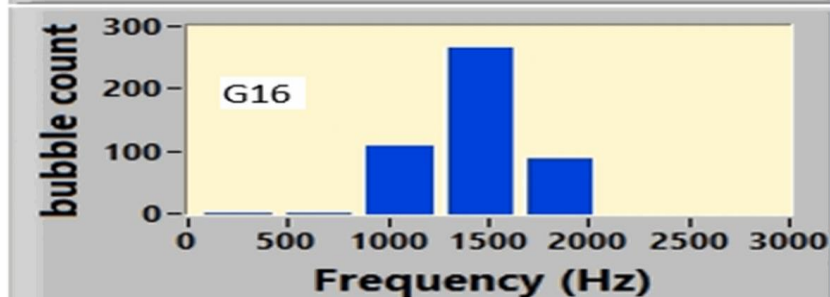
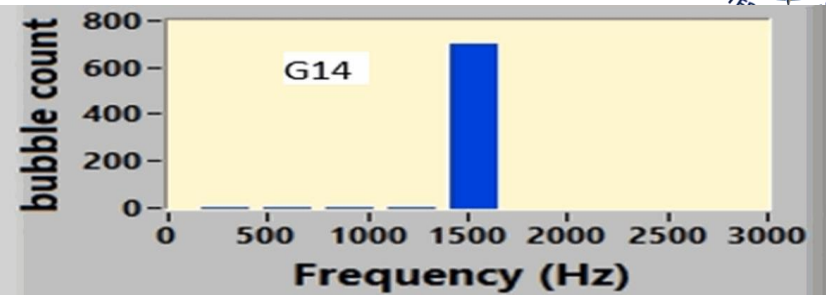
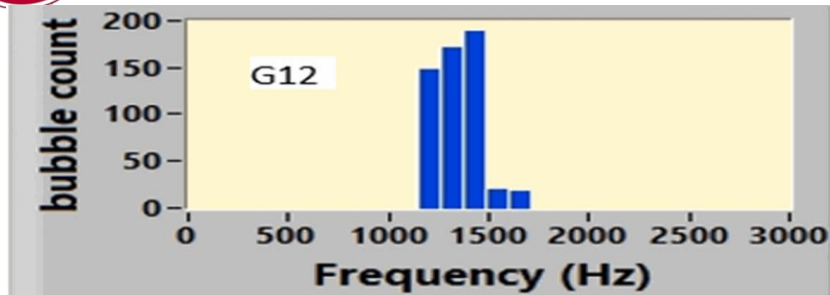


Total energy vs jet velocity (for constant flow)





Resonant frequency vs needle size



Minnaert resonance frequency

$$\omega_M = \frac{1}{R_0} \sqrt{\frac{3\gamma\rho_0}{\rho}}$$



Conclusions

- Localization algorithms were able to determine the locations of bubble sources
- Acoustic signatures in terms of total energy and resonate frequency can be used to estimate the intensity and crack size of oil leakages.



Future works

- Repeat the tests on methane
- Study the bubble sound mechanisms
- Build a hydrophone array to measure the direction of arrivals (DOAs)
- Develop algorithms using the DOAs for localization.



Acknowledgment

Funding from Gulf Research Program of the National Academy of Sciences with award number: 2000008860.

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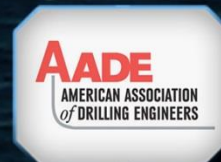
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QUESTIONS

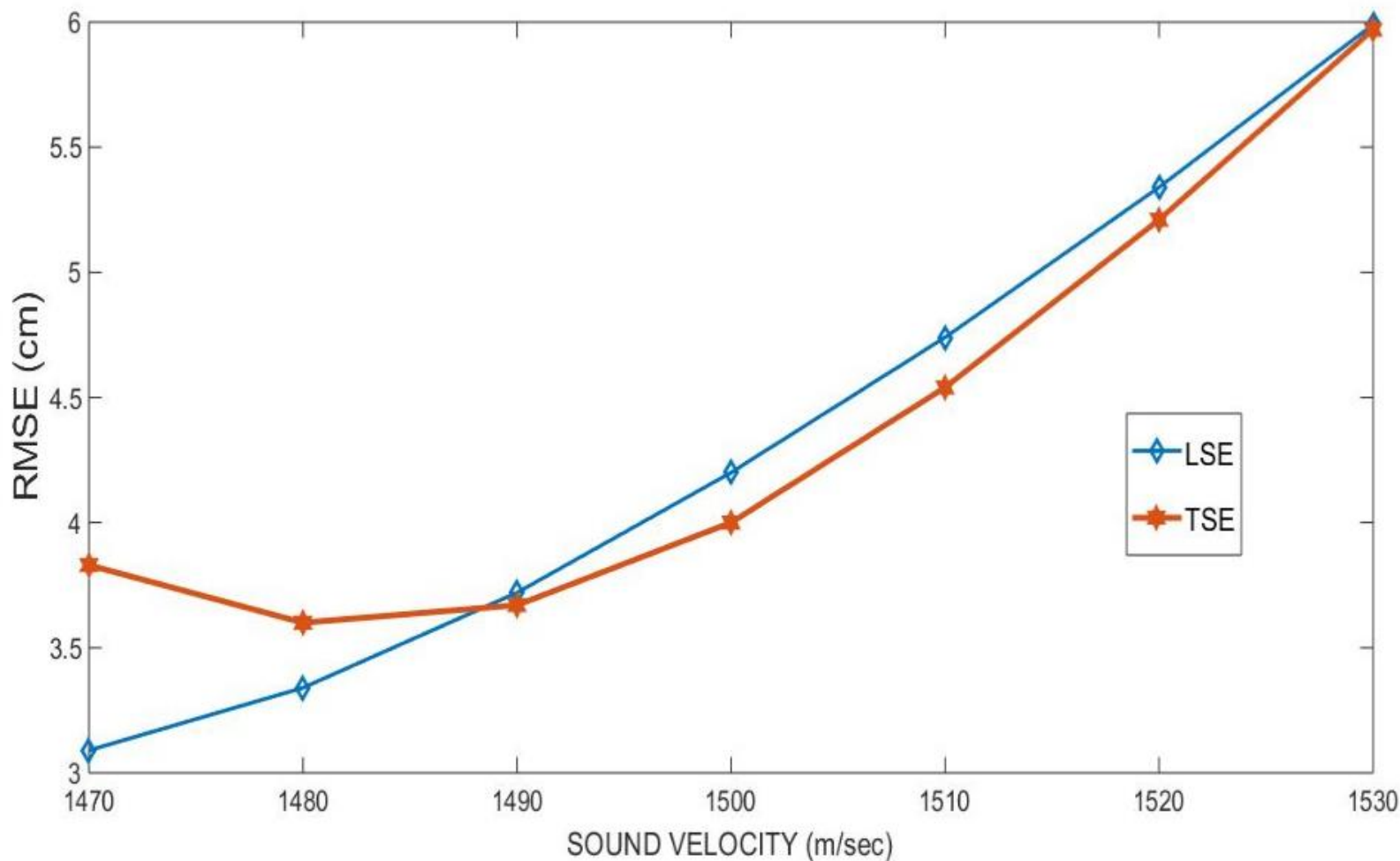
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Zhiqu Lu
The University of Mississippi





Calibration of sound speed with an active hydrophone

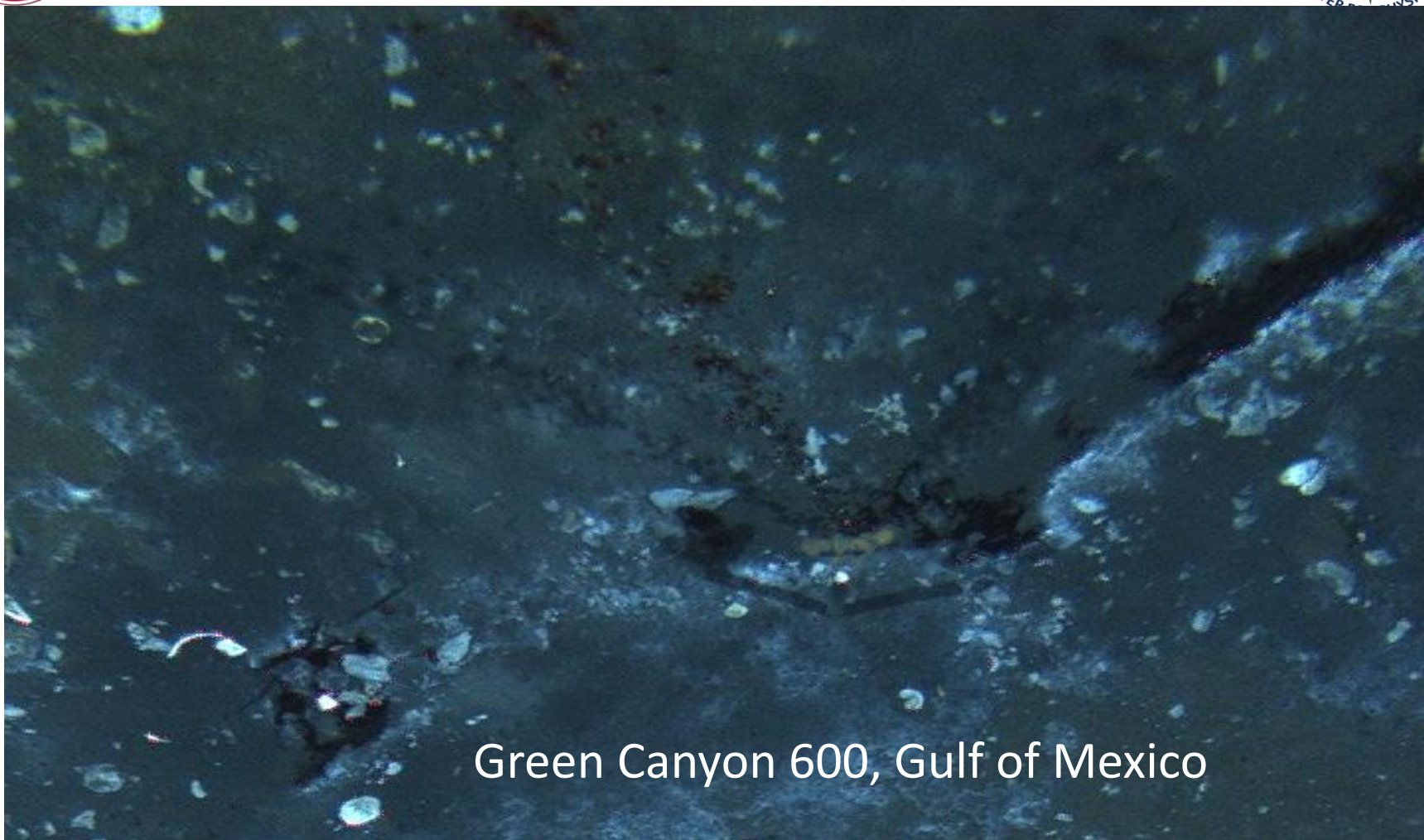


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Sea floor seepage



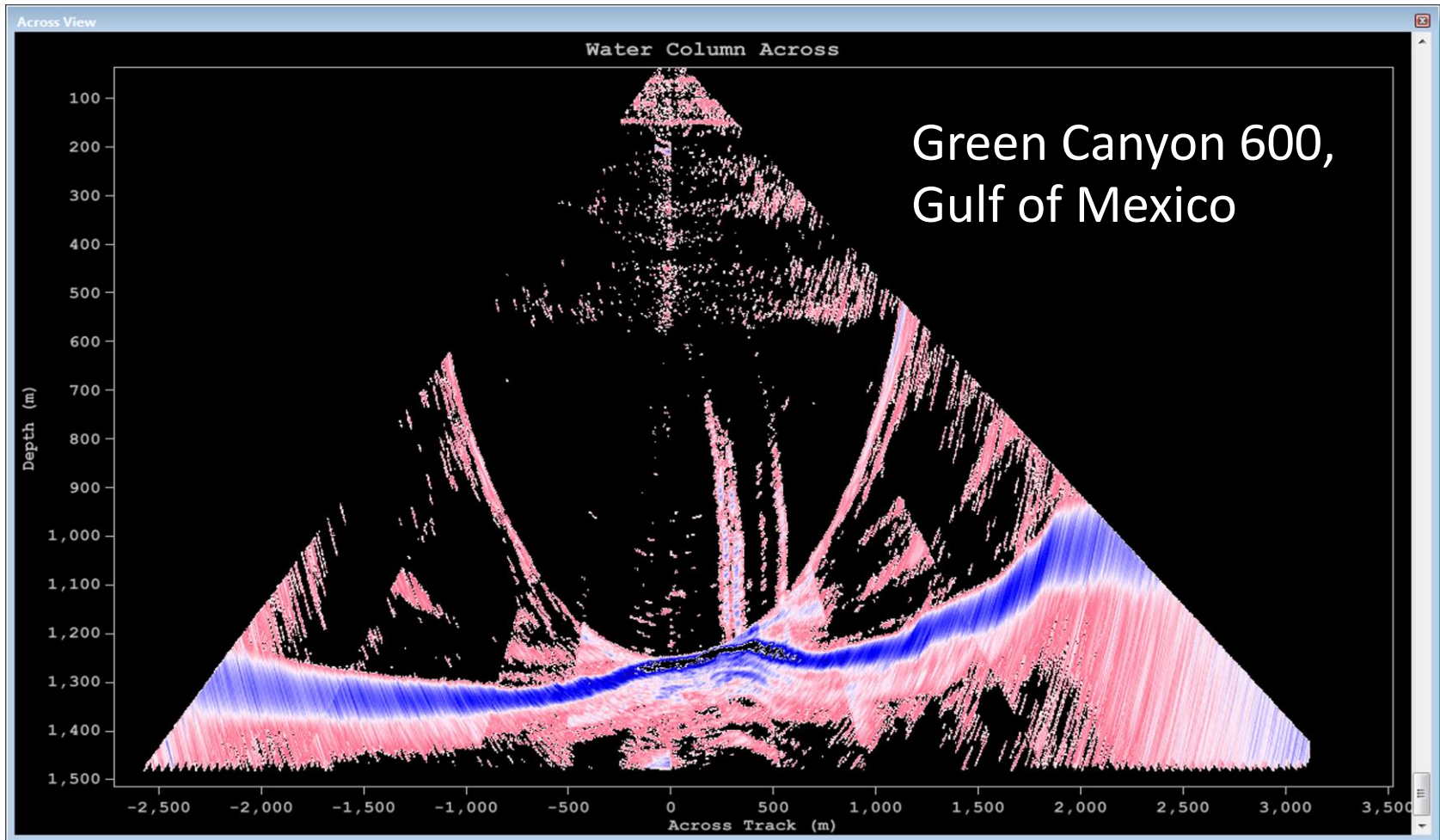
Green Canyon 600, Gulf of Mexico

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Multi-beam sonar image of sea floor seepage

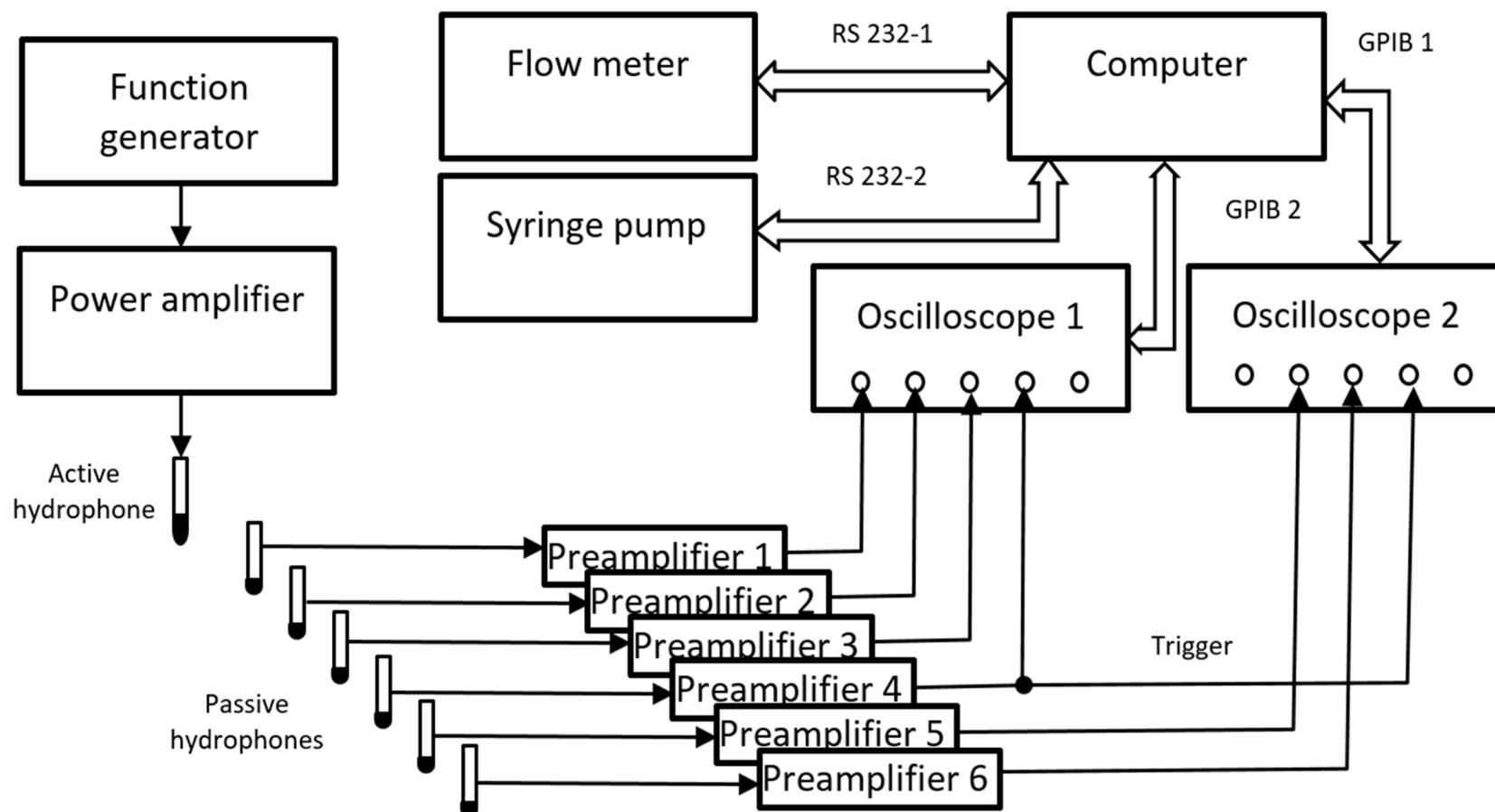


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Data Acquisition





**22nd Annual Gulf of Mexico, Deepwater Technical
Symposium, New Orleans, LA.**

**Session: "Integrated Engineering & Geoscience Research in
the Gulf of Mexico".**

Presentation: 8:30 AM – 9:00 AM, Aug 29, 2018

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